

Information Transport and Synchronization in a Spatially Extended Predator-Prey Model.

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Problem:

- We can't monitor all populations everywhere in a large region.
- Much work has been done on **indicator species** that assess ecological health of a region.
- What about **indicator areas**? Are there some that are **better** (or **worse**) at assessing population in the **region**?

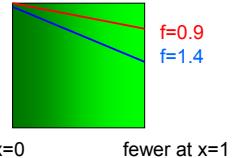
Spatially Extended Predator-Prey Model (Pascual, 1993)

$$\partial p/\partial t = r_x p(1-p) - [ap/(1+bp)]h + d(\partial^2 p/\partial x^2)$$

(pred. death rate) $m = .6$, (diffusion coeff.) $d = 10^{-4}$,
 (bdry res. Level) $e = 5.0$, (carrying cap.) $b = 2.0$
 (coupling coeff.) $a = 5.0$, Two cases: $f=0.9$, $f=1.4$

$$r_x = e - fx$$

Varying Resource Gradient

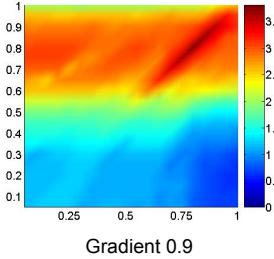


Jonzen et al (2005) looked at monitoring in a **source/sink** environment. In a **sink**, a population **can't be supported** without diffusion.
 In this model the **low-resource end still can support a population**. How might monitoring strategies **differ**?
 We will assess strategies using **information flow** and **synchronization** properties of the model.

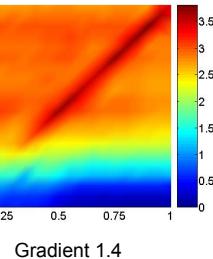
Information Transport: Transfer Entropy (Schreiber, 2000)

$$TE_{Y \rightarrow X} = \sum p(x_{i+1}, x_i, y_j) \log_2(p(x_{i+1}|x_i, y_j)/p(x_{i+1}|x_i))$$

Transfer Entropy measures the amount of **additional** information about **dynamics in X** that **Y contributes**

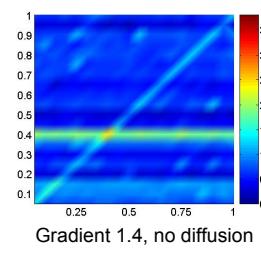


Gradient 0.9



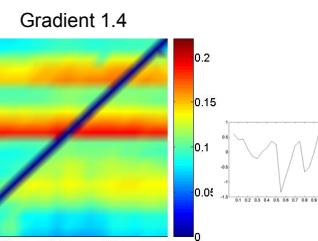
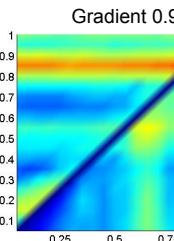
Gradient 1.4

Predator to Prey Transfer Entropy shows **information flow** from high-resource end to low-resource end. The **low resource end** contains **more information**. Without diffusion, there is no "downhill" information flow.



Gradient 1.4, no diffusion

Information flow from one **site** to another (both species). Small plots show **net** information flow (flow out minus flow in). **Peaks** in the graph are areas that contain **more** information about other areas' dynamics... What about the **troughs**? Transfer entropy is **zero** if dynamics are **identical** to another sites'. It is **zero** If the **dynamics are independent**. What do we do...?

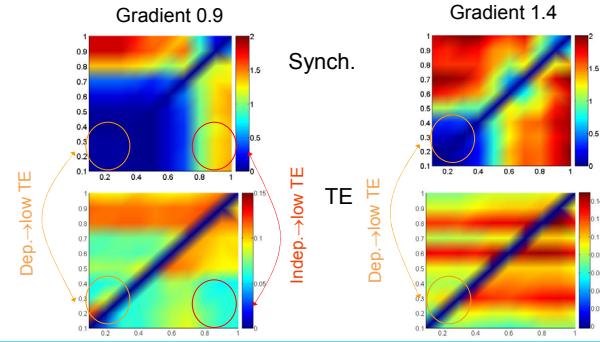


Synchronization: Time-Delayed Continuity

Generalized Synchronization between two sites X and Y is the existence of a continuous function between the two sites. We can also add a time delay in Y to see if the dynamics "flow", that is, they synchronize at some time in the future:

$$F: X \rightarrow Y \text{ so that } F(x) = y(x+t).$$

We use a variant on the **Continuity Test** found in Nichols et al (2005). This test indicates why TE is zero – **independence or dependence**?



REFERENCES:

- Pascual, M. Diffusion-induced chaos in a spatial predator-prey system. Proc. Roy. Soc. B **251**, 1-7 (1993)
 Schreiber, T. Measuring Information Transfer. Physical Review Letters **85**, 462-464 (2000)
 Nichols, J.M., Moniz, L, Nichols, J.D., Pecora,L.M. , Cooch, E. Assessing spatial coupling in complex population dynamics using mutual prediction and continuity statistics. Theoretical Population Biology **67**, 9-21 (2005)
 Jonzen, N., Rhodes, J.B., Possingham, H.P. Trend detection in source-sink systems: When should sink habitats be monitored? Ecological Applications **15** (1) 326-334 (2005)